

Robot Inspection Checklist

Team Number: _____

Size Inspection

<input type="checkbox"/> Robot fits within starting size restrictions (18" x 18" x 18") without touching walls or ceiling of the sizing tool. During match play, no horizontal dimension exceeds 36". Team ID Plates must be installed for sizing inspection.	R4, SG14
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Overall Inspection

<input type="checkbox"/> Team is only competing with ONE robot. They have no spare or replacement robots.	R1
<input type="checkbox"/> Robot displays colored VEX Team Identification plates on at least (2) opposing sides.	R19
<input type="checkbox"/> Robot does NOT contain any components which will be intentionally detached on the playing-field.	G11
<input type="checkbox"/> Robot does NOT contain any components that could entangle or damage the playing-field or other robots.	R3
<input type="checkbox"/> Robot does NOT contain any sharp edges or corners.	R3
<input type="checkbox"/> Robot on/off switch is accessible & Microcontroller lights are visible without moving or lifting the robot.	R16

VEX Parts Inspection

<input type="checkbox"/> ALL Robot components are (or are IDENTICAL to) OFFICIAL VEX Products as sold on VEXrobotics.com (No 3D printed functional parts are allowed)	R5, R6, R7
<input type="checkbox"/> Robot does not use VEX products not intended for use as a robot component or any VEX packaging.	R5b
<input type="checkbox"/> ALL Components on the Robot NOT meeting VRC Inspection Criteria are NON-FUNCTIONAL decorations	R7d
<input type="checkbox"/> Any grease is used only in moderation on components that do not contact the field, objects, or other robots.	R7e
<input type="checkbox"/> Any non-shattering plastic on the robot was cut from a single sheet of 0.070" material not larger than 12"x24".	R7f
<input type="checkbox"/> Robot has only (1) VEX EDR Microcontroller.	R9
<input type="checkbox"/> Robot utilizes the VEXnet wireless communication system.	R10
<input type="checkbox"/> None of the electronics are from the VEXplorer, VEXpro, VEX-RCR, VEX IQ, or VEX Robotics by Hexbug.	R10b
<input type="checkbox"/> Total number of Servos and Motors is not more than twelve (12) without use of pneumatics or ten (10) with use of pneumatics.	R11
<input type="checkbox"/> Each 2-wire motor is plugged into its own 2-wire port or into a Model 29 motor controller	R11-2a
<input type="checkbox"/> A motor may only be controlled by a single controller port	R11-2b
<input type="checkbox"/> Robot uses a maximum of (1) Y-Cable per each 3-wire Motor Port (cannot "Y" off a 2-wire Motor Port)	R12
<input type="checkbox"/> Robot uses (1) VEX 7.2V (Robot) Power Pack as the primary power source.	R13
<input type="checkbox"/> If the Robot has a Power Expander, it has a 2nd 7.2V (Robot) Power Pack	R13
<input type="checkbox"/> Robot uses a maximum of (1) VEX Power Expander	R13b
<input type="checkbox"/> Robot has a charged 9V Backup Battery connected	R13c
<input type="checkbox"/> Team only utilize VEX Battery Chargers for charging VEX 7.2V Battery Packs	R13e
<input type="checkbox"/> Robot is not controlled by more than (2) VEX hand-held transmitters.	R14
<input type="checkbox"/> NO VEX electrical components have been modified from their original state.	R15a
<input type="checkbox"/> NO Method of attachment NOT provided by the VEX Design System is used. (Welding, Gluing, etc.)	R15b
<input type="checkbox"/> Robot uses a maximum of two (2) VEX pneumatic air reservoirs. (Maximum 100 psi per air reservoir)	R18

Field Control Check

<input type="checkbox"/> Robot successfully completes the "Field Control Check" Procedure. See Inspection Guidelines.	R21
<input type="checkbox"/> Robot enters Autonomous mode when prompted with no driver control for duration of Autonomous.	R20
<input type="checkbox"/> The Hand-held Controller(s) ONLY control the robot when robot is in Driver mode.	R20

PTC Verification Testing

Failure to pass this test will result in immediate Event Disqualification	Pass/Fail: _____	Tested By: _____	R15, R21
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Final Inspection Pass/Fail: _____

Inspector Signature: _____

Team Initials: _____